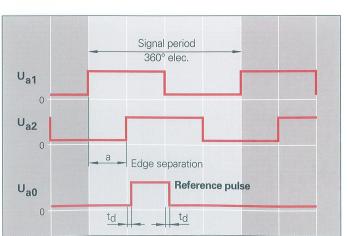
## **Output Signals**

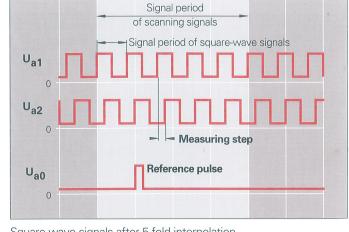
Encoders with TTL square-wave output signals incorporate electronics that digitize non-interpolated or 5 to 10-fold interpolated sinusoidal scanning signals. They provide two 90° (elec.) phase-shifted TTL square-wave pulses U<sub>a1</sub> and U<sub>a2</sub> and one or more **reference pulses U<sub>a0</sub>** that are gated with the incremental signals. A fault-detection signal  $\overline{U_{aS}}$  indicates fault conditions such as an interruption in the supply lines or light failure. The integrated electronics also output the inverted signals of all square-wave signals.

The measuring step results from the distance between two successive edges of the signals U<sub>a1</sub> and U<sub>a2</sub> through 1-fold, 2-fold, or 4-fold evaluation.

To ensure reliable operation, the input circuitry of the subsequent electronics must be designed to detect every edge of the square-wave pulses. To avoid errors in counting, the maximum permissible traversing speed for the selected edge separation a must not be exceeded.

	LS 176, LS 476, LS 323, LS 623   Square-wave signals $\square \square \square \square \square$ Two TTL square-wave signals $U_{a1}$ and $U_{a2}$ and their inverse signals $\overline{U_{a1}}$ , $\overline{U_{a2}}$		
Output signals Incremental signals			
<b>Reference mark signal</b> Pulse width	1 or more square-wave pulses $U_{a0}$ and their inverted pulse $\overline{U_{a0}}$ 90° elec. or 270° elec. (option)		
Fault detection signal	1 square-wave pulse U <sub>aS</sub> Improper function: LOW (optional: output U <sub>a1</sub> /U <sub>a2</sub> high impedance) Proper function: HIGH		
Signal levels	Differential line driver as per EIA standard RS-422 $U_H \ge 2.5$ V at $-I_H = 20$ mA $U_L \le 0.5$ V at $I_L = 20$ mA		
Permissible load	$R \geq 100 \; \Omega \qquad \qquad \text{(terminating resistor between the associated outputs)}$ $II_{L}I \leq 20 \; \text{mA} \qquad \qquad \text{(max. load per output)}$ $C_{Load} \leq 1000 \; \text{pF}  \text{against 0 V}$ $Outputs \; \text{protected against short circuit to 0 V}$		
Switching times (10% to 90%)	Rise time $t_{+} \le 50 \text{ ns}$ Fall time $t_{-} \le 50 \text{ ns}$ With 1 m cable and recommended input circuitry		
Connecting cable	HEIDENHAIN cable with shielding PUR [4(2 × 0.14 mm²) + (4 × 0.5 mm²)]		
Cable length	Max. 100 m (329 ft) distributed capacitance 90 pF/m		





Square-wave signals without previous interpolation

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Square-wave signals after 5-fold interpolation

	LS 176 LS 476		LS 623	LS 323
Interpolation	5-fold <sup>1)</sup>	10-fold <sup>1)</sup>	None	
Measuring step (after 4-fold evaluation)	1 μm	0.5 μm	5 μm	
Edge separation <sup>1)</sup> at max. permissible traversing speed	≥ 0.25 µs; 120 m/min <sup>2)</sup> ≥ 0.5 µs; 120 m/min ≥ 1 µs; 60 m/min	≥ 0.25 µs; 120 m/min ≥ 0.5 µs; 60 m/min ≥ 1 µs; 30 m/min	≥ 2.5 µs; 60 m/min	≥ 1.25 µs; 120 m/min
Delay time of reference pulse	lt <sub>d</sub> l ≤ 50 ns			_3)
Fault detection signal	Yes		No	
<sup>1)</sup> Please indicate when orc <sup>2)</sup> Mechanical limit <sup>3)</sup> Reference pulse pop-gate				

Reference pulse non-gated

## **□** □ TTL: Recommended input circuitry of subsequent electronics

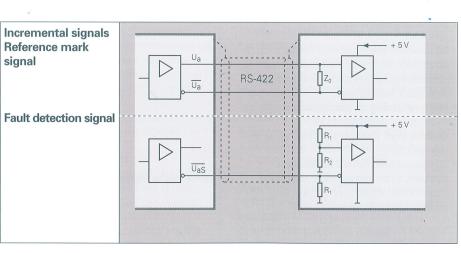
## Dimensioning

Recommended differential line receiver AM 26 LS 32 MC 3486 SN 75 ALS 193  $R_1 = 4.7 \text{ k}\Omega$  $R_2 = 1.8 \text{ k}\Omega$ 

Fault detection signal

Reference mark

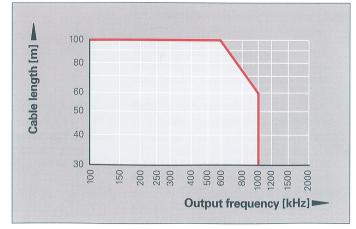
signal



## Cable lengths

 $Z_0 = 120 \Omega$ 

TTL square-wave signals can be transmitted to the subsequent electronics by cable up to 100 m (329 ft), provided that the 5 V ± 5% supply voltage is maintained at the encoder. The voltage received by the encoder can be measured from the subsequent electronics through sensor lines and corrected, if required, by a control system. (See also Explanations of Specifications.)



Permissible cable length with respect to output frequency